

Computational challenges in assessment of marine resources

Hans Julius skaug

Talk given at Inst. of Informatics, UiB

Nov. 28, 2002

Outline

- Mathematical ecology
 - Management of living resources
- Computation and statistics
 - Models
 - Numerical integration in high dimensions
 - Automatic differentiation
- Examples of 'assessment problems'
 - Harp seals

Institute of Marine Research



- Units
 - Bergen, Tromsø, Flødevigen, Austevoll, Matre
- 500 employees
 - 135 researches
- Center for marine resources
 - Fish (cod, herring, capelin, ...)
 - Whales and seals

Management of living resources

- ‘Assessment’ = Estimation of
 - Current stock size
 - Biological parameters: mortality rates, birth rates, ...
- Prediction of future stock size
 - Given today’s status
 - Under a given management regime (quota)
- Principles
 - Maximize harvest
 - Minimize risk of extinction
- Uncertainty
 - Important for determining risk

The complication

- Acoustic and trawl surveys do NOT give absolute estimates of stock size

$$I = q \cdot U$$

where

I = survey index

U = stock size

Population dynamics

u_t = stock size at time t

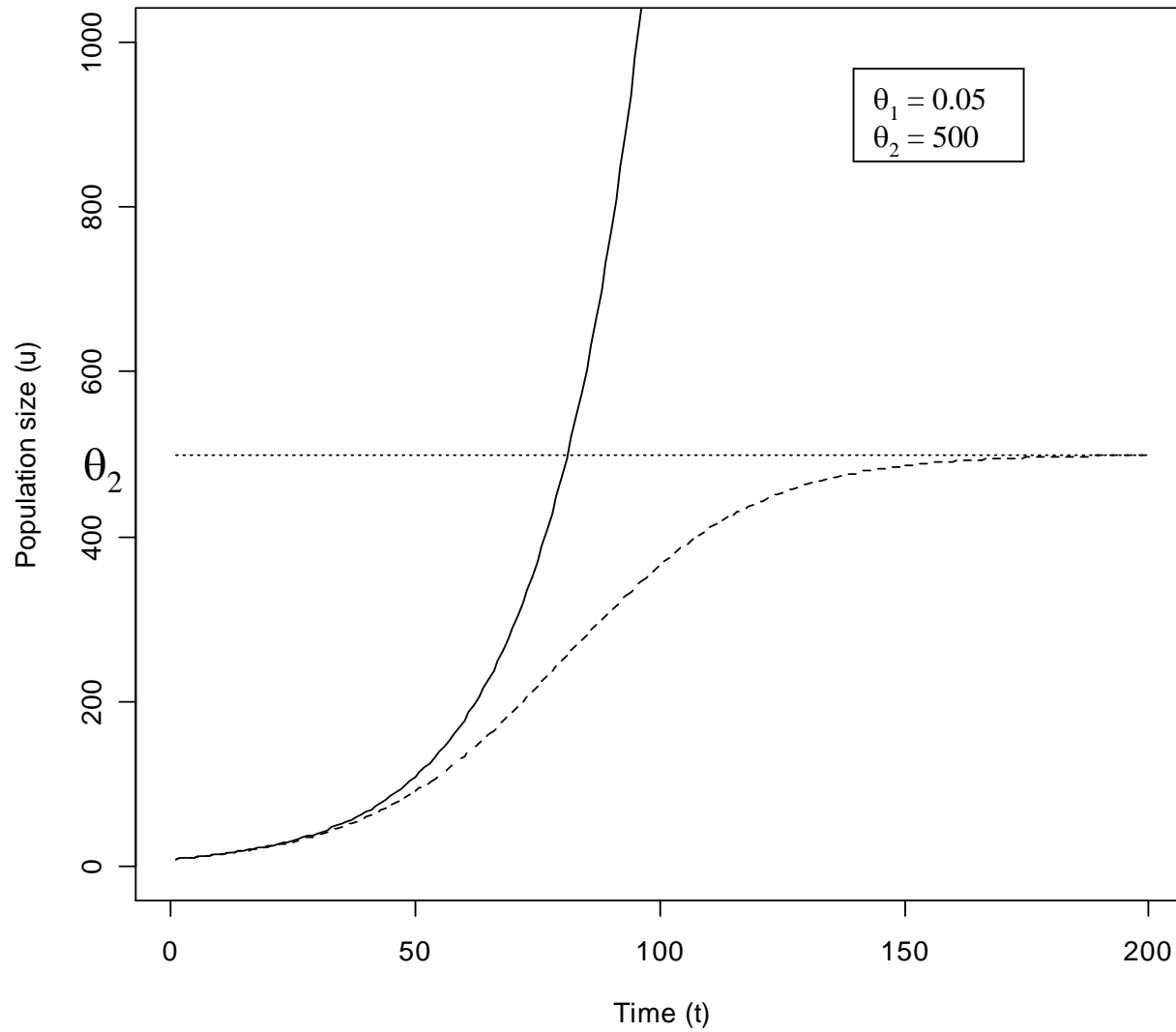
- Exponential growth

$$u_t = u_{t-1} \cdot (1 + \theta_1)$$

- Density regulation

$$u_t = u_{t-1} \cdot [1 + \theta_1(1 - u_{t-1}/\theta_2)]$$

Population growth



Population dynamics

- Exponential growth

$$u_t = u_{t-1} \cdot (1 + \theta_1)$$

- Density regulation

$$u_t = u_{t-1} \cdot [1 + \theta_1(1 - u_{t-1}/\theta_2)]$$

- Harvest

$$u_t = (u_{t-1} - c_{t-1}) \cdot [1 + \theta_1(1 - u_{t-1}/\theta_2)]$$

- Stochastic growth rate

$$u_t = (u_{t-1} - c_{t-1}) \cdot [1 + \theta_1(1 - u_{t-1}/\theta_2) + \mathbf{N}(0, \theta_3)_t]$$

Additional complexity

- Age structure
- Spatial structure
- Interactions with other species
- Effect of environment

Models in statistics

- Parameters
 - θ structural parameter, $\dim(\theta) \approx 20$
 - u state parameter, $\dim(u) \approx 1000$
- Data
 - y ‘measurements’
- Probability distributions
 - $p(y | u, \theta)$ probability of data given u and θ
 - $p(u | \theta)$ probability of u given θ
 - $p(\theta)$ ‘prior’ on θ

State-space model

- State equation $p(\mathbf{u} \mid \theta)$

$$u_t = (u_{t-1} - c_{t-1}) \cdot [1 + \theta_1(1 - u_{t-1}/\theta_2) + N(0, \theta_3)_t]$$

- Observation equation $p(\mathbf{y} \mid \mathbf{u}, \theta)$

$$y_t = \theta_4 \cdot u_t + N(0, \theta_5)_t$$

Models in statistics

- Joint probability distribution

$$p(y,u,\theta) = p(y|u,\theta) \cdot p(u|\theta) \cdot p(\theta)$$

- Marginal distribution

$$p(y,\theta) = \int p(y,u,\theta) \, du$$

Statistical computation

- Major challenge (today)

$$p(y, \theta) = \int p(y, u, \theta) du$$

- Maximum likelihood estimation θ

$$\underline{\theta} = \operatorname{argmax}_{\theta} p(y, \theta)$$

Algorithms

- Simple Monte Carlo integration
- Importance sampling
- Markov Chain Monte Carlo
 - Metropolis-Hastings algorithm
 - Gibbs sampler
- EM-algorithm
- Kalman filter (nonlinear)

Laplace approximation

$$p(\mathbf{y}, \theta) = \int p(\mathbf{y}, \mathbf{u}, \theta) d\mathbf{u}$$

$$L(\theta) = |\det(\mathbf{H})|^{-1/2} p(\mathbf{y}, \hat{\mathbf{u}}, \theta)$$

$$\hat{\mathbf{u}}(\theta) = \arg \max_{\mathbf{u}} p(\mathbf{y}, \mathbf{u}, \theta),$$

$$\mathbf{H}(\theta) = \frac{\partial^2}{\partial \mathbf{u}^2} \log[p(\mathbf{y}, \mathbf{u}, \theta)] |_{\mathbf{u}=\hat{\mathbf{u}}_\theta}$$

Pierre-Simon Laplace (1749-1827)

- Bayes formula

$$p(u|y) = p(y|u) \cdot p(u) / p(y)$$

where

$$p(y) = \int p(y|u) \cdot p(u) du$$

- Replaces integration with maximization
- Exact for the Gaussian case



Maximum likelihood estimation

- Estimate θ by maximizing $L(\theta)$
- Gradient $\nabla_{\theta}L$ by automatic differentiation

AD (Automatic Differentiation)

- Given that we have a code for L
- AD gives you $\nabla_{\theta}L$
 - at machine precision
 - 'no' extra programming
 - efficiently (reverse mode AD)
$$\text{cost}(\nabla_{\theta}L) \approx 4 \cdot \text{cost}(L)$$
- AD people
 - Bischof, Griewank, Steihaug,
- Software: ADIFOR, ADOL-C, ADMB ...

Laplace approximation again

$$L(\theta) = |\det(\mathbf{H})|^{-1/2} p(\mathbf{y}, \hat{\mathbf{u}}, \theta)$$

where

$$\hat{\mathbf{u}}(\theta) = \arg \max_{\mathbf{u}} p(\mathbf{y}, \mathbf{u}, \theta),$$

$$\mathbf{H}(\theta) = \frac{\partial^2}{\partial \mathbf{u}^2} \log[p(\mathbf{y}, \mathbf{u}, \theta)] \Big|_{\mathbf{u}=\hat{\mathbf{u}}_\theta}$$

Research questions

- AD versus analytical formulae
 - Which is the most efficient?
- Higher order derivatives (3th order)
 - Less efficient than the gradient
- Sparseness structure

Constrained optimization formulation

Maximize jointly w.r.t. \mathbf{u} and θ

$$L(\theta, \mathbf{u}) = |\det[\mathbf{H}(\mathbf{u}, \theta)]|^{-1/2} p(\mathbf{y}, \mathbf{u}, \theta)$$

under the constraint

$$\frac{\partial}{\partial \mathbf{u}} \log[p(\mathbf{y}, \mathbf{u}, \theta)] = 0$$

BeMatA project

- NFR- funded (2002-2005)
- Collaboration between:
 - Inst. of Marine Research
 - Inst. of informatics, UiB
 - University of Oslo
 - Norwegian Computing Center, Oslo
- Joins expertise in
 - Statistical modeling
 - Computer science / Optimization

Fisheries assessments

- Age determination of fishes invented around 1900
 - like counting growth layers in a tree

- 'Fundamental law'

$$u_{t,a} = (u_{t-1,a-1} - c_{t-1,a-1}) \cdot (1 - \theta)$$

- t is an index of year
- a is an index of year
- θ is mortality rate

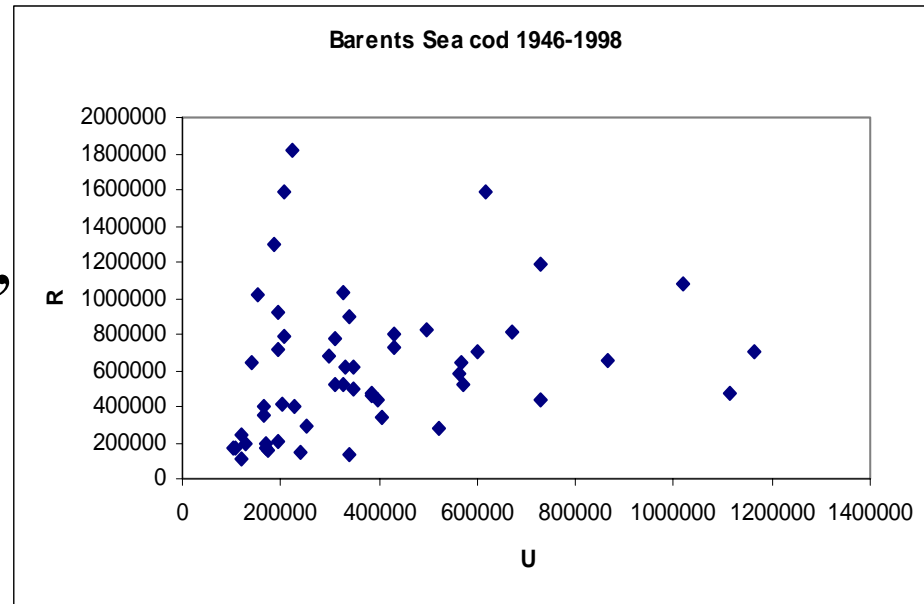
Recruitment mechanism

- Number of spawners

$$U_t = \sum_a u_{t,a}$$

- Number of fish 'born'

$$u_{t,0} = R(U_t, \theta)$$

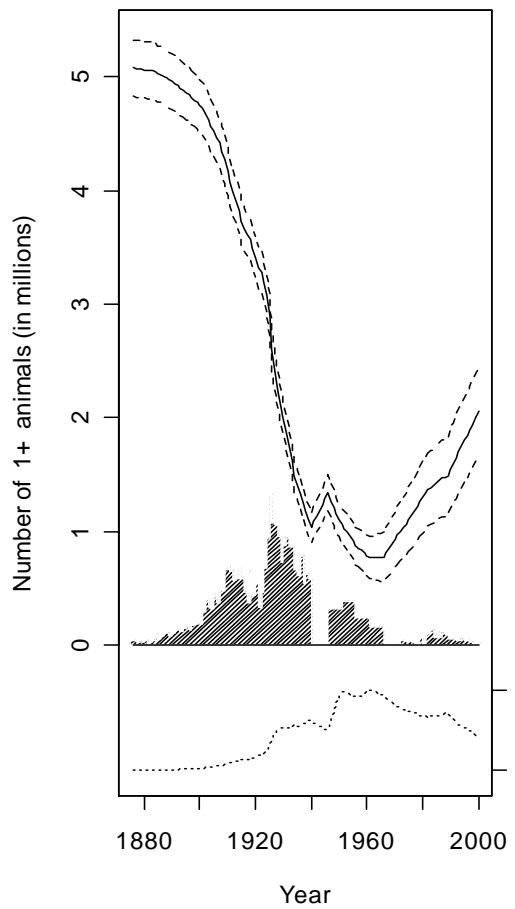


- Strong relationship: seals
- Weak relationship: herring

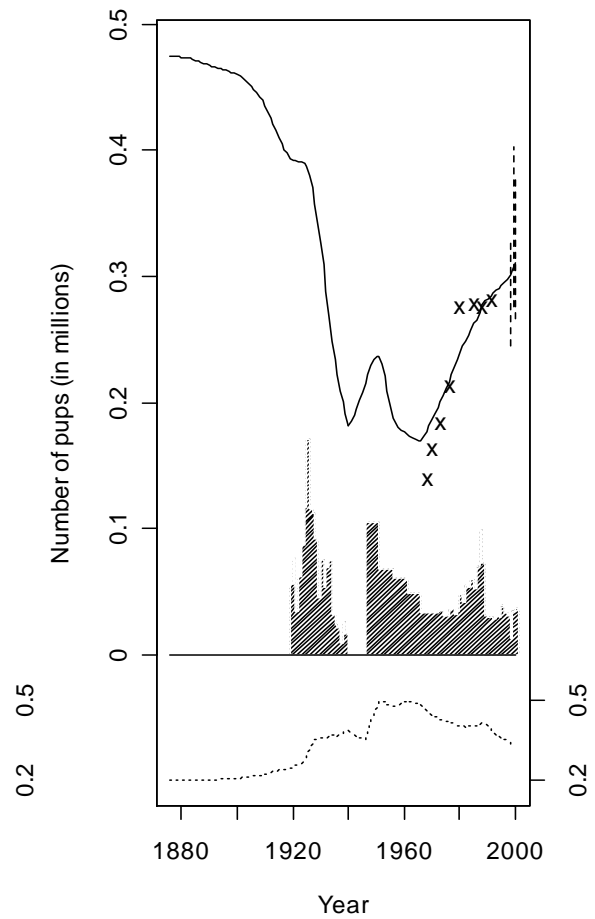
Case study: Harp seals

- Barents Sea stock
 - Currently 2 million individuals
- Data
 - Historical catch records
 - Only pups can be counted
 - Age samples on whelping grounds
- Questions
 - Pre-exploitation stock size
 - Lowest level attained by the stock

a: 1+ population



b: Pups



Annotated references

BeMatA project

Title: Latent variable models handled with optimization aided by automatic differentiation; application to marine resource

<http://bemata.imr.no/>

State-space models in fisheries

Gudmundsson, G. (1994). Time-series analysis of catch-at-age observations, *Applied Statistics*, **43**, p. 117-126.

AD

Griewank, A. (2000). Evaluating Derivatives: Principles and Techniques of Algorithmic Differentiation, *SIAM, Philadelphia*.

AD and statistics

Skaug, H.J. (2002). Automatic differentiation to facilitate maximum likelihood estimation in nonlinear random effects models. *Journal of Computational and Graphical Statistics*. 11 p. 458-470.

Laplace approximation in statistics

Tierney, L. and Kadane, J.B. (1986). Accurate approximations for posterior moments and marginal distributions. *Journal of the American Statistical Association* 81 p. 82-86